APPROXIMATE SUPERMODULARITY BOUNDS FOR EXPERIMENTAL DESIGN

CONTRIBUTIONS i. The greedy solution of the A-optimal design problem is $(1 - e^{-\alpha})$ -optimal with $\alpha \ge [1 + \mathcal{O}(\mathsf{SNR})]^{-1}$. ii. The value of the greedy solution of an **E-optimal design problem** is at most $(1 - e^{-1})(f(\mathcal{D}^{\star}) + k\epsilon)$, where $\epsilon \leq \mathcal{O}(\mathsf{SNR})$. iii. As the SNR of the experiments decreases, the performance guarantees for greedy A- and E-optimal designs approach 1 - 1/e. **INTRODUCTION** Experimental design = select which experiments to run or measurements to observe to estimate a variable of interest Applications: designing experiments, semi-supervised learning, multivariate analysis, sketching, sensor placement... ► NP-hard in general, P approximations for *supermodular* objectives estimation MSE (A-optimality) and spectral norm of error covariance matrix (E-optimality) are not *supermodular* **EXPERIMENTAL DESIGN** \blacktriangleright Pool of experiments \mathcal{E} $y_e = \boldsymbol{A}_e^T \boldsymbol{\theta} + \boldsymbol{v}_e$ $\mathbb{E}(\boldsymbol{\theta} - \bar{\boldsymbol{\theta}})(\boldsymbol{\theta} - \bar{\boldsymbol{\theta}})^T = \boldsymbol{R}_{\boldsymbol{\theta}} \qquad \boldsymbol{v}_e \sim \mathcal{N}(\boldsymbol{0}, \boldsymbol{R}_e)$ $\mathbb{E}\,oldsymbol{ heta}=ar{oldsymbol{ heta}}$ ▶ Design $\mathcal{D} \in \mathcal{P}(\mathcal{E})$ (multiset) \blacktriangleright Use the experiments in \mathcal{D} to estimate $oldsymbol{z} = oldsymbol{H}oldsymbol{ heta}$ Proposition (Bayesian estimator) Given a design $\mathcal{D} \in \mathcal{P}(\mathcal{E})$, the unbiased affine estimator of \boldsymbol{z} with the smallest error covariance matrix in the PSD cone is given by $\hat{\boldsymbol{z}}_{\mathcal{D}} = \mathbb{E}[\boldsymbol{z} \mid \boldsymbol{\theta}, \boldsymbol{v}_{e}] = [\text{long uninformative expression}]$ with error covariance matrix $\boldsymbol{K}(\mathcal{D}) = \boldsymbol{H} \left[\boldsymbol{R}_{\theta}^{-1} + \sum_{e \in \mathcal{D}} \boldsymbol{A}_{e}^{T} \boldsymbol{R}_{e}^{-1} \boldsymbol{A}_{e} \right]^{-1} \boldsymbol{H}^{T}.$ **OPTIMAL EXPERIMENTAL DESIGN** A-optimal (NOT supermodular) $\underset{|\mathcal{D}| < k}{\text{minimize}} \quad \text{Tr}\left[\boldsymbol{K}(\mathcal{D})\right] - C_A$ E-optimal (NOT supermodular) $\underset{|\mathcal{D}| < k}{\text{minimize}} \quad \lambda_{\max} \left[\mathbf{K}(\mathcal{D}) \right] - C_E$ D-optimal (supermodular) $\min_{\substack{|\mathcal{D}| < k}} \log \det \left[\mathbf{K}(\mathcal{D}) \right] - C_D$

Luiz F. O. Chamon and Alejandro Ribeiro

e-mail: luizf@seas.upenn.edu, Electrical & Systems Engineering, University of Pennsylvania



NEAR-E-OPTIMAL DESIGN







RELATED WORK

Optimal experimental design

- [Ageev'04, Horel'14]
- [Wang'17]

Greedy non-submodular optimization

- [Horel'16]

CONCLUSION

Greedy A- and E-optimal experimental design is guaranteed to work well despite the fact that their objectives are not supermodular.



Convex relaxation (SDPs or sequential SOCPs) [Flaherty'06, Joshi'09, Sagnol'11, Horel'14, Wang'17] \blacktriangleright D-optimal design: (1 - 1/e) guarantee using pipage rounding

 \blacktriangleright A-optimal design: near-optimal randomized schemes for large k

 \blacktriangleright ϵ -supermodularity with constant ϵ [Krause'10]

 \blacktriangleright α -supermodularity with constant α [Chamon'16]

 \blacktriangleright submodularity ratio (γ) bounds using RIP [Das'11], RSC

[Elenberg'16], and spectral inequalities [Bian'17]

► [Chamon'16, Bian'17] do not account for multisets: 2.5×10^{-6} -optimality vs 0.1-optimality (A-optimality, SNR = 0 dB)

 \blacktriangleright more stringent approximate submodularity (" δ -submodularity") function must be upper and lower bounded by a submodular function

> approximate submodularity is sometimes called weak submodularity (e.g., [Elenberg'16]), not to be confused with weak submodularity in [Borodin'14]